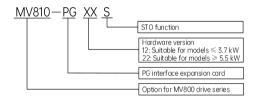
MV800 Resolver PG Card (with STO Function) User Manual

BOM code: R******

Version: V00

1 Product Information

1.1 Naming rule



1.2 Function description

MV810-PG*2S is an accessory card for the MV800 series AC drive, which provides encoder interfaces, with resolver signal input, serving as the speed or position feedback. It has two ways of STO signal input to achieve Safe Torque Off for the AC drive.

1.3 Product appearance

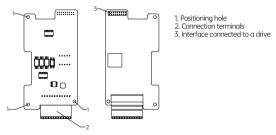
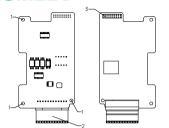


Fig. 1-1 PG*2S appearance (for models of 3.7 kW and below)



- 1. Positionina hole
- Connection terminals
 Interface connected to a drive

Fig. 1-2 PG*2S appearance (for models of 5.5 kW and above)

1.4 Terminal description

The following figure shows the terminal marks of MV810-PG*2S.

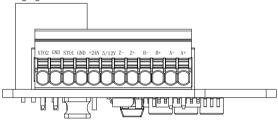


Fig. 1-3 Terminal mark

The terminal definitions of MV810-PG*2S are shown in the following table.

Table 1-1 PG*2S terminal functions

Type	Mark	Name	Function description	Specifications
MV810- PG*2S card	S+, S-	Encoder SIN+/- signal	Encoder SIN feedback input signal	
	C+, C-	Encoder COS+/- signal	Encoder COS feedback input signal	2 Vrms±10%
	E+, E-	Encoder EXC+/- signal	Excitation signal output end for the external encoder	4 Vrms±10% 10kHz
	PE	Encoder power	Reference ground PE of encoder power supply	-

Туре	Mark	Name	Function description	Specifications
		ground		
	+24V	STO1, 2 power +	When not using the STO function, you can connect this terminal to STO1 and STO2 to disable the STO function (by default).	Output voltage: +24 V±10% Max. output current: 100 mA
	STO1	STO1 terminal	STO1 function input 1	Optocoupler isolation.
	STO2	STO2 terminal	STO2 function input 2	By default, the STO1 and STO2 are
	GND	STO1, 2 ND power Ground for 5/12V, +24V ground	connected to +24V with a short contact tag. External 24 V wiring is available, which is shown in the STO wiring diagram below mentioned.	

1.5 Signal description

The excitation signal EXC and feedback signals SIN/COS of MV810-PG*2S are shown in the following figure.

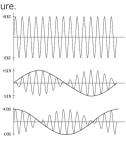


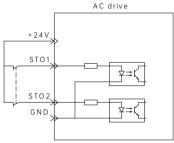
Fig. 1-4 Resolver signal

□ Note

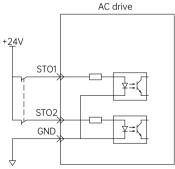
- (1) When the motor rotates forward, the COS signal leads the SIN signal by 90° . When the motor rotates reversely, the SIN signal leads the COS signal by 90° .
- (2) The selection of a resolver must meet the parameter requirements of MV810-PG*2S, and especially the input DC resistance of excitation must be greater than $17 \,^{\Omega}$. Otherwise, MV810-PG*2S will not function properly.
- (3) To prevent MV810-PG*2S from being overloaded due to the selection of a resolver with too many pole pairs, it is advisable not to choose a resolver with pole pairs higher than 4.

1.6 STO wiring diagram

(1) Internal 24 V wiring diagram



(2) External 24 V wiring diagram





- ① If you do not use the STO function, you need to short STO1 and STO2 to +24V according to one of the wiring diagrams above. For wiring, it is recommended to use tubular terminals such as Guosai's EVN0510 (double-wire) and Semikron's E0208 (single-wire). The recommended cable is 0.2 mm² (AVVR) or 24 AWG (UL1007).
- ② For other terminals, such as encoder signals and power supply signals, it is also advised to use the abovementioned tubular terminals and cables.

1.7 Related function codes

Here are explanations of table fields for function codes.

Field	Explanation	
Default	Factory settings of function codes	
Property	O: means the function code can be changed during running; x: means the function code can be changed at stop; *: means the function code can be read only and cannot be changed.	

Function code	Name	Description	Default	Property
P04.00	Encoder PPR	1 to 65535	1024	×
P04.01	Encoder type	0: No encoder 1: ABZ incremental encoder 2: Resolver encoder	0	0
P04.02	Encoder direction	0: Forward 1: Reverse Note: Rotation auto-tuning automatically detects the phase sequence	0 to 1	0
P04.07	Initial position of synchronous motor	The initial position of synchronous motor corresponding to the absolute encoder	0	×

Function code	Name	Description	Default	Property
		0 to 360.0		
P04.08	Resolver	0: Disabled	0 to 1	0
	correction enable	1: Enabled	0 10 1	

2 Installation

The installation position, installation interface and installation steps for MV810-PG*2S are described below.

2.1 Installation position of PG card

MV800 series AC drive provides two positions for expansion cards and options, as shown in Fig. 2-1 position 1 and position 2 (taking enclosure B as an example, similar for other enclosures), where position 1 is for the installation of various PG/PG+STO cards and position 2 is for the installation of PN bus options, ECAT bus options, I/O options, and so on.



Fig. 2-1 Expansion card/Option installation positions

2.2 Installation interface of PG card

The electrical interface of PG*2S card is connected to the MV800 AC drive as shown in Fig. 2-2.



Fig. 2-2 Installation interface of PG card

2.3 Installation steps of PG card

Installation method: Reverse side mounting (PG*2S card)

(1) When the drive is powered off, press the granulated part on the middle-upper of the lower cover, and slide it down firmly to take down the cover, as shown in Fig. 2-3 a.

- (2) Use a straight screwdriver to pry open the two snap-fit joints between the control box and the drive, and then remove the control box upwards, as shown in Fig. 2-3 b and c.
- (3) Install the PG*2S card: Hold the PG*2S card with its terminal block downwards, then align the three round holes on the PG*2S card with the location column, and press down to buckle the PG*2S card firmly into the four snap-fit joints, as shown in Fig. 2-3 d.
- (4) After the PG card is installed, align the control box with the snap-fit joints, and press down the control box to make its lower part firmly buckled, then slide the lower cover to lock it on the drive, as shown in Fig. 2-3 e and f.

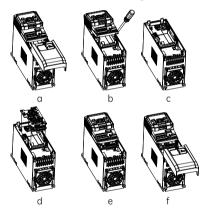


Fig. 2-3 Position 1 - PG card installation steps

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Warranty bill of com	munication option		Checker:	
Customer company:		MEGMEET	Manufacturing date:	
Detailed address:				
Contact:	Tel:	SHENZHEN		
Option model:		MEGMEET	The product has	
Option No:		ELECTRICAL CO.,	been tested in line with design	
Purchase date:			standards and	
		Certificate	approved for leaving	
Service unit:			the factory.	
Contact:	Tel:			
Maintenance date:				